

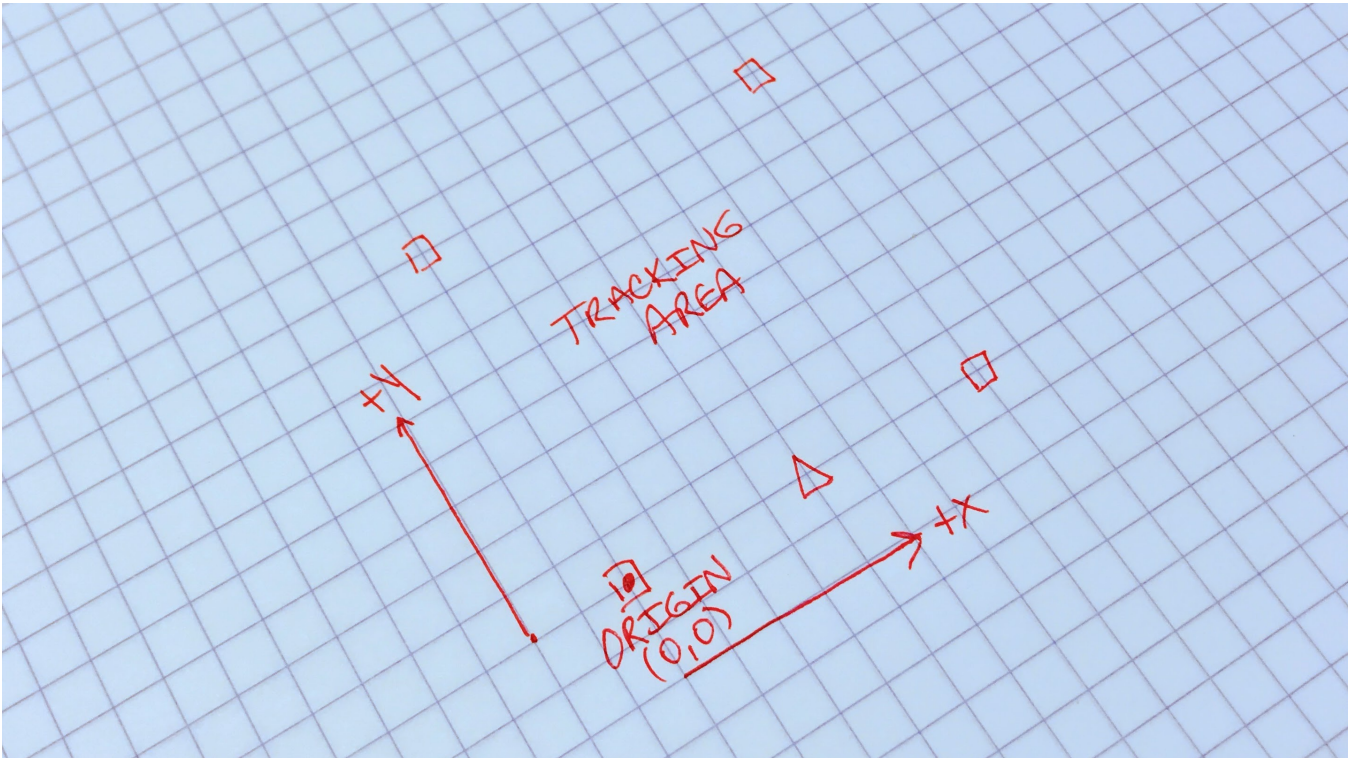


The Archimedes revision of the Ciholas Ultra-Wideband (CUWB) system is designed for developers to test and evaluate UWB technologies. The following quick start documentation is intended as a guide for new users to quickly start and operate an Archimedes network.

This guide is not intended for advanced setup, for further detail regarding the various system options please see the [Archimedes User Manual](#).

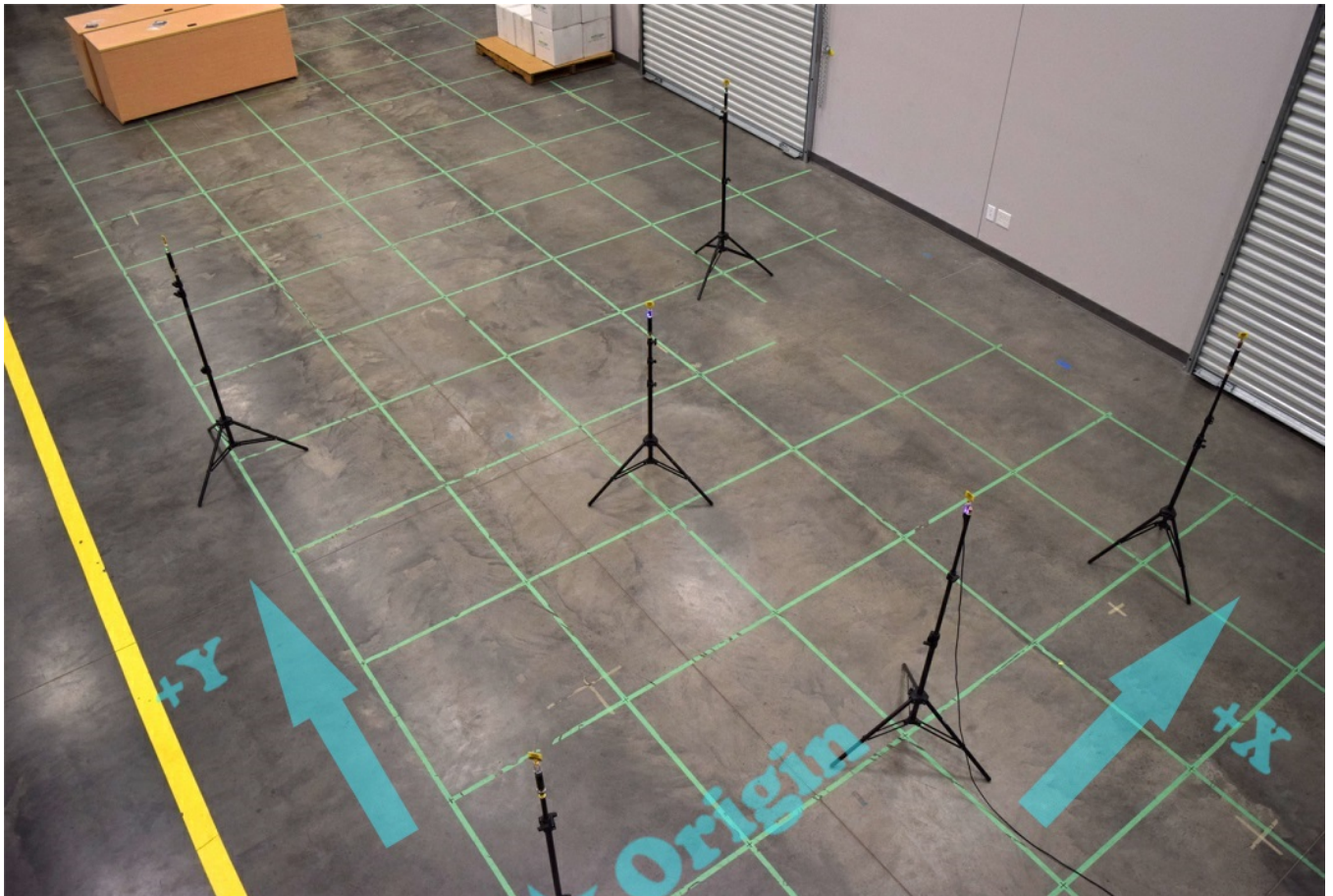
1. Setup

1. Determine Anchor and Master Locations .
 - All anchors require line of sight visibility to master.
 - Tags require line of site visibility to four or more anchors.
 - Anchor location selection should initially prioritize the perimeter of the intended tracking area. Fill in the interior area with additional anchors if possible.
2. Determine axis orientation and origin.



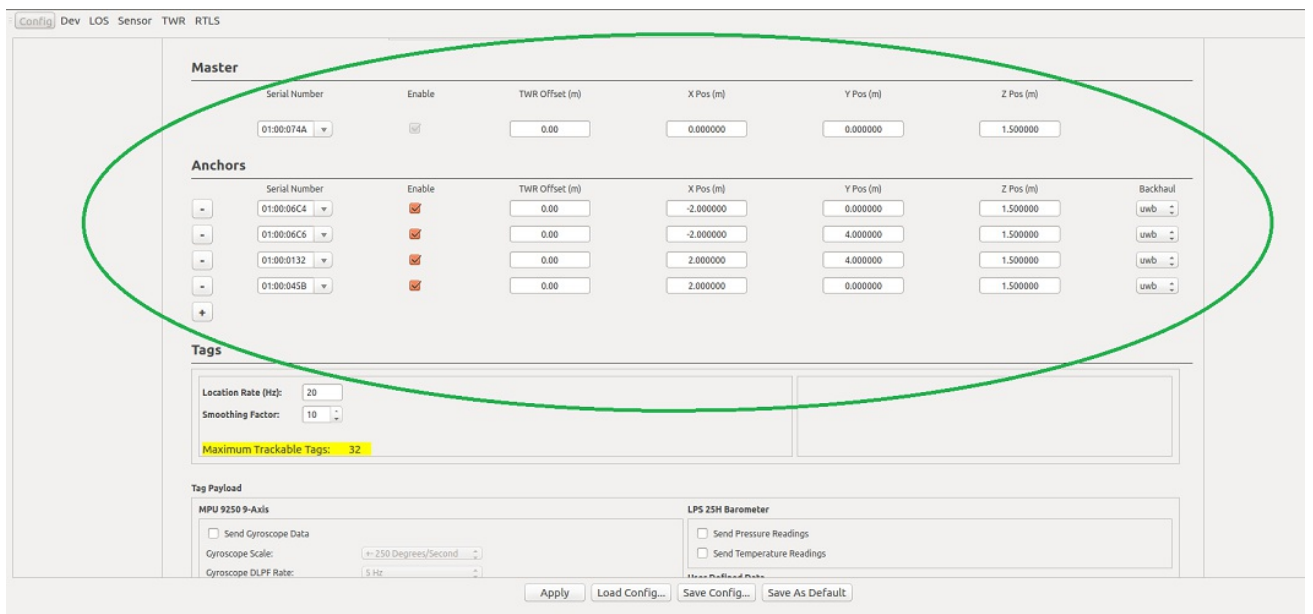
3. Survey anchor and master locations relative to the origin and desired XYZ axes. Measurements should be in meters.





4. CUWB Server Installation:

o



o Input tag information into CUWB Server GUI in the *Available Tags* section (Serial Number).

Config Dev LOS Sensor TWR RTLS

Location Rate (Hz): 20
Smoothing Factor: 10
Maximum Trackable Tags: 32

Tag Payload

MPU 9250 9-Axis

Send Gyroscope Data
Gyroscope Scale: +-250 Degrees/Second
Gyroscope DLPF Rate: 5 Hz
 Send Accelerometer Data
Accelerometer Scale: +-2G
Accelerometer DLPF Rate: 5 Hz
 Send Quaternions
MPU Data Rate Divisor (1 kHz / val): 5 Sample Rate: 200 Hz
MPU Subsample Rate Divisor: 5 Send Rate: 40 Hz
 Send Magnetometer Data (8 Hz)

LPS 25H Barometer

Send Pressure Readings
 Send Temperature Readings

User Defined Data

Payload Size: 0 bytes
Payload Frequency: 1 Hz

Payload Headroom

0 bytes

Available Tags

Serial Number	Enable	TWR Offset (m)
01:00:0733	<input checked="" type="checkbox"/>	0.00

Tag Bounds

X (m): -3.000000 to: 5.000000 Y (m): -1.000000 to: 5.000000 Z (m): 0.000000 to: 1.400000

Apply Load Config... Save Config... Save As Default

- Set Tag *Location Rate (Hz)* in the *Tags* section. This determines the rate locations are calculated, and impacts the maximum number of tags that can be tracked (Displayed in this section of the application).

Config Dev LOS Sensor TWR RTLS

Master

Serial Number	Enable	TWR Offset (m)	X Pos (m)	Y Pos (m)	Z Pos (m)
01:00:074A	<input checked="" type="checkbox"/>	0.00	0.000000	0.000000	1.500000

Anchors

Serial Number	Enable	TWR Offset (m)	X Pos (m)	Y Pos (m)	Z Pos (m)	Backhaul
01:00:06C4	<input checked="" type="checkbox"/>	0.00	-2.000000	0.000000	1.500000	uwb
01:00:06C6	<input checked="" type="checkbox"/>	0.00	-2.000000	4.000000	1.500000	uwb
01:00:0132	<input checked="" type="checkbox"/>	0.00	2.000000	4.000000	1.500000	uwb
01:00:045B	<input checked="" type="checkbox"/>	0.00	2.000000	0.000000	1.500000	uwb

Tags

Location Rate (Hz): 20
Smoothing Factor: 10
Maximum Trackable Tags: 32

Tag Payload

MPU 9250 9-Axis

Send Gyroscope Data
Gyroscope Scale: +-250 Degrees/Second
Gyroscope DLPF Rate: 5 Hz
 Send Accelerometer Data
Accelerometer Scale: +-2G
Accelerometer DLPF Rate: 5 Hz
 Send Quaternions
MPU Data Rate Divisor (1 kHz / val): 5 Sample Rate: 200 Hz
MPU Subsample Rate Divisor: 5 Send Rate: 40 Hz
 Send Magnetometer Data (8 Hz)

LPS 25H Barometer

Send Pressure Readings
 Send Temperature Readings

User Defined Data

Payload Size: 0 bytes
Payload Frequency: 1 Hz

Payload Headroom

0 bytes

Apply Load Config... Save Config... Save As Default

- Set *Tag Bounds*. Expand no more than 1-3 meters beyond the anchor perimeter.

Config Dev LOS Sensor TWR RTLS

Location Rate (Hz): 20
Smoothing Factor: 10
Maximum Trackable Tags: 32

Tag Payload

MPU 9250 9-Axis

Send Gyroscope Data
Gyroscope Scale: +-250 Degrees/Second
Gyroscope DLPF Rate: 5 Hz
 Send Accelerometer Data
Accelerometer Scale: +-2G
Accelerometer DLPF Rate: 5 Hz
 Send Quaternions
MPU Data Rate Divisor (1 kHz / val): 5 Sample Rate: 200 Hz
MPU Subsample Rate Divisor: 5 Send Rate: 40 Hz
 Send Magnetometer Data (8 Hz)

LPS 25H Barometer

Send Pressure Readings
 Send Temperature Readings

User Defined Data

Payload Size: 0 bytes
Payload Frequency: 1 Hz

Payload Headroom

0 bytes

Available Tags

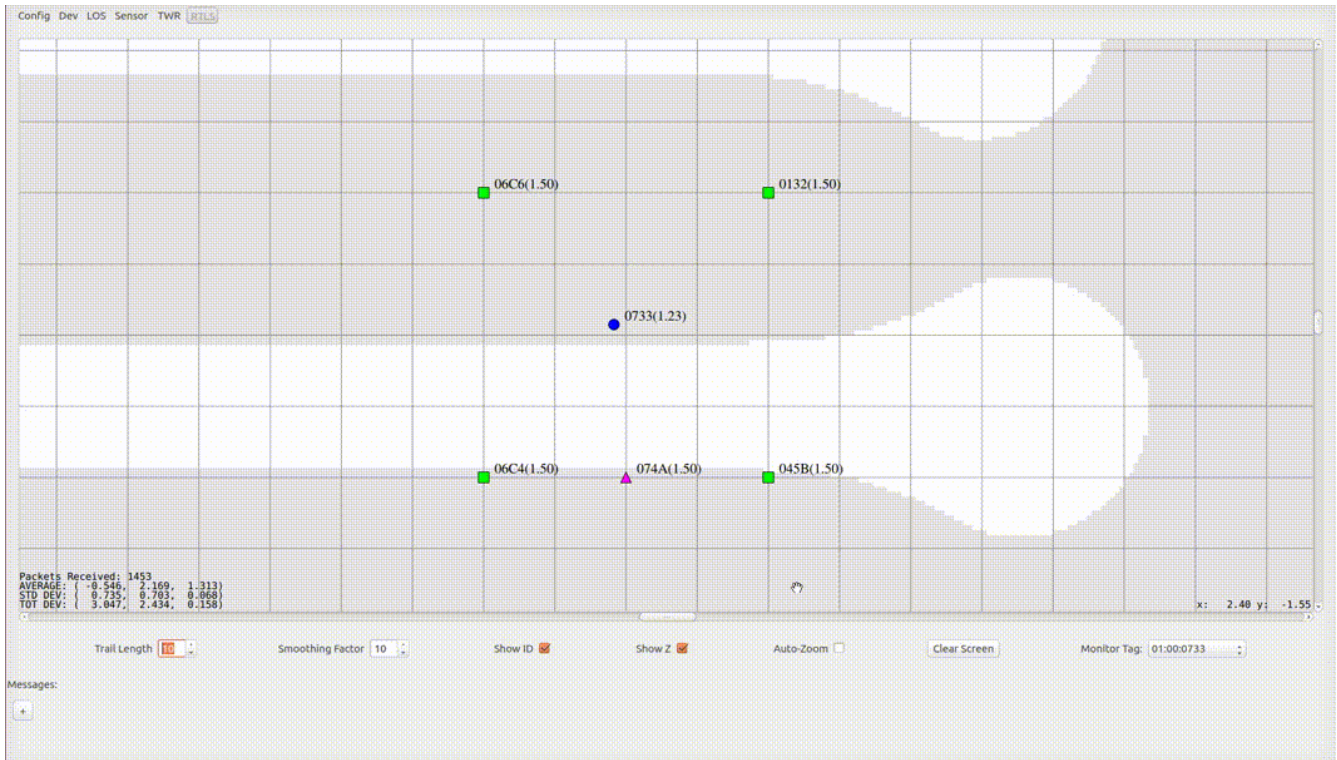
Serial Number	Enable	TWR Offset (m)
01:00:0733	<input checked="" type="checkbox"/>	0.00

Tag Bounds

X (m): -3.000000 to: 5.000000 Y (m): -1.000000 to: 5.000000 Z (m): 0.000000 to: 1.400000

Apply Load Config... Save Config... Save As Default

2. Operation



1. Enter the *RTLS* tab in the CUWB Server application (Far right tab). This starts network operation.
2. Components are displayed in the GUI as follows:

Device	Representation	Inactive Color	Active Color
Master	Triangle	Gray	Purple
Anchor	Square	Gray	Green
Tag	Circle	Gray	Blue

3. Device LEDs will match the colors represented in the GUI
4. Adjust *Smoothing Factor* (averaging) and *Trail Length* located below the tracking area in the application if desired. *Note: that increasing smoothing increases positional latency.*
5. To stop network operation, leave the *RTLS* tab or close the application.

3. Additional Information

These links provide further information regarding Archimedes network setup and operation:

- For installation and usage instruction check out the [User Manual](#)
- Software and Binaries can be found in the [Downloads](#) section

Please visit the following links for more information and documentation regarding [Ciholas](#) UWB systems and products:

- Documentation, installation, and usage instructions visit [CUWB.io](#)
- To purchase [Ciholas](#) UWB products please visit the [Ciholas Shop](#)
- Ask other users questions and find community information in the [Community Forum](#)
- Learn more about Ciholas services at www.ciholas.com